# Description

The ME22 is a reliable low cost optical hollow shaft encoder that can be fixed quickly and easily on different sizes of motor shafts.

The encoder provides two square wave outputs in quadrature (90 degrees phase shifted) for counting and direction information and one optional index channel (one pulse per revolution). The resolution of the encoder is determined by the number of counts per revolution (CPR). Power supply and signals are provided by a 5 pin Molex connector.

Dimensions
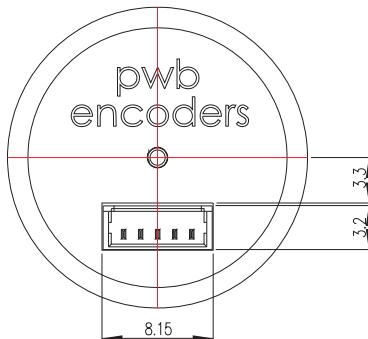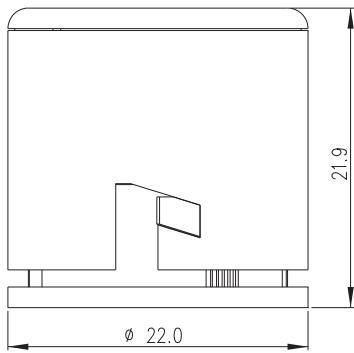
Encoder Resolution (CPR)
001
002
004
008
050
064
100
108
120
124
125
128
150
160
200
250
256
300
360

Features

- Small size: 22.0 mm diameter x 21.9 mm length.
- Quick and easy assembly without touching sensitive components
- Output channels: 2 (quadrature) + 1 optional index-channel
- Power supply: 5 VDC
- Output type: TTL compatible
- Output circuit: pull-up
- Resolution up to 360 CPR (counts per revolution)
- Maximum shaft diameter: 9.525 mm (3/8")
- Operating temperature: -20 °C to 85 °C
- Frequency: 60 kHz
- Compliant EU-directive 2002/95/EG (RoHS)

Motor shaft Ø Diameter (mm)
1.500
2.000
2.300
2.500
3.000
3.175 (1/8")
3.969 (5/32")
4.000
4.763 (3/16")
5.000
6.000
6.350 (1/4")
8.000
9.000
9.525 (3/8")

Recommended operating conditions

Electrical characteristics are only effective for the range of the operating temperatures. Typical values at 25 °C and V_{CC} = 5 VDC.

Parameter	Symbol	Min.	Typ.	Max.	Unit	Notes
Operating temperature	T_A	-20	25	85	°C	
Supply voltage	V_{cc}	4.5	5.0	5.5	V_{DC}	
Supply current (two channels)	I_{cc}	13	15	18	mA	
Supply current (three channels)	I_{cc}	33	35	38	mA	
Load capacitance	C_L			100	pF	internal pull-up 2.7 kΩ
Count frequency	f			60	kHz	rpm x N / 60 x 10^{-3}
A & B Channel						
High level output voltage	V_{oH}	2.4		Vcc	V_{DC}	I_{oH} = -0.2 mA
Low level output voltage	V_{oL}			0.4	V_{DC}	I_{oL} = 8.0 mA
Rise time	t_r		$500 / (7)^2$		$ns / (\mu s)^2$	C_L = 25 pF;
Fall time	t_f		$100 / (1.3)^2$		$ns / (\mu s)^2$	R_L = 2.7 kΩ
Index Channel						
High level output voltage	V_{oH}	2.4		Vcc	V_{DC}	I_{oH} = -0.2 mA
Low level output voltage	V_{oL}			0.4	V_{DC}	I_{oL} = 8.0 mA
Rise time	t_r		7		µs	C_L = 25 pF;
Fall time	t_f		1.3		µs	R_L = 2.7 kΩ

1. on demand
2. only for 1,2,4,8 CPR variant

Absolute maximum ratings

Parameter	Symbol	Min.	Typ.	Max.	Unit	Notes
Storage temperature	T_s	-40		85	°C	
Operating temperature	T_A	-20		85	°C	
Humidity exposure				90	% RH	not condensing
Supply voltage	V_{cc}	-0.5		7	V_{DC}	
Output voltage	V_o	-0.5		V_{cc}	V_{DC}	
Output current per channel	I_{out}	-1.0		8	mA	
Vibration				2000	Hz	20 g

ESD Warning: Normal handling precautions should be taken to avoid static discharge damage to the sensor.

Electrical interface
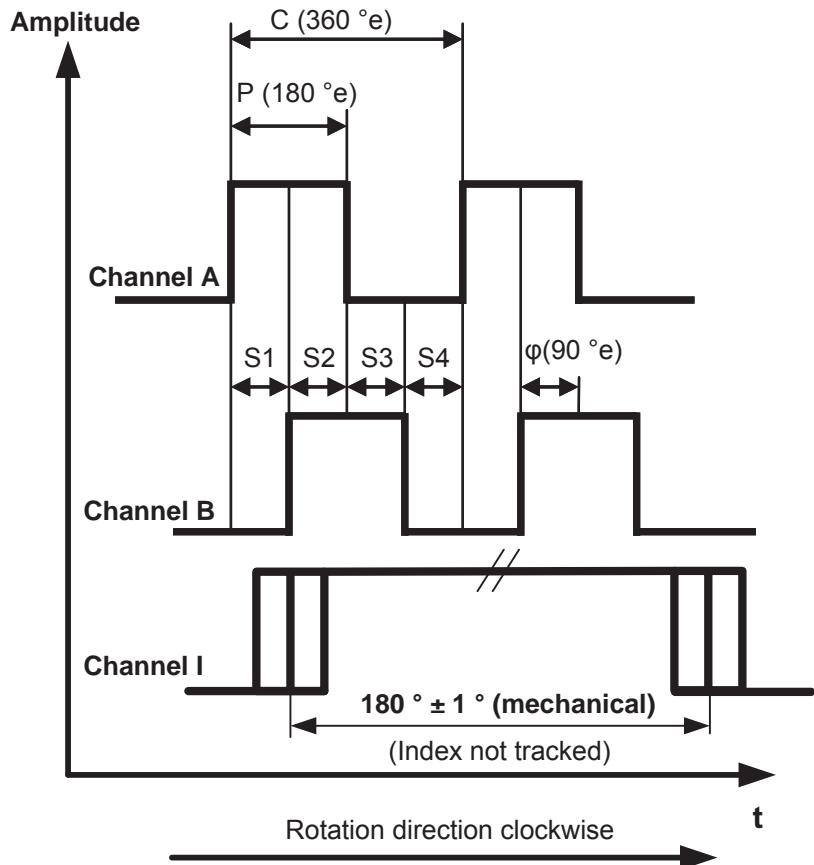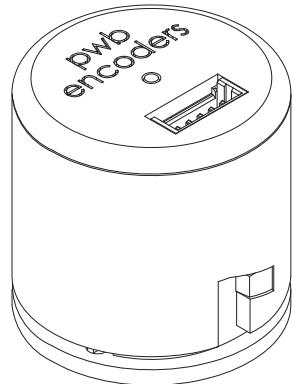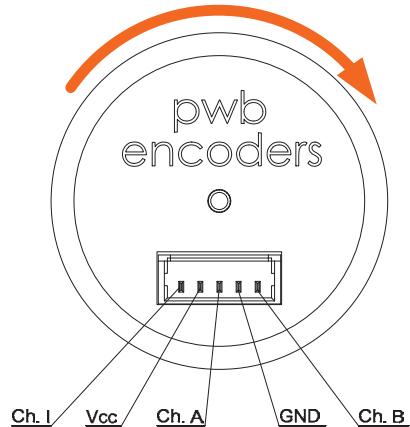
Definitions

Counts per Revolution (CPR):
The number of bar and window pairs or increments per revolution of the code wheel.

One Cycle (C):
360 electrical degrees (°e), one period of the signal, caused by one pair of bar and window.

Pulse Width (P):
The number of electrical degrees that an output is high during one cycle. This value is nominally 180 °e.

State Width (S):
The number of electrical degrees between a transition in the output of channel A and the neighbouring transition in the output of channel B. There are 4 states per cycle, each nominally 90 °e.

Phase (φ):
The number of electrical degrees between the centre of the high state of channel A and the center of the high state of channel B. This value is nominally 90 °e.

Position Error (ΔQ):
The angular difference between the actual angular shaft position and the position indicated by the encoder cycle count.

## Encoding characteristics channel A & B

Parameter	Symbol	Nominal	Max.Error	Unit
Pulse width	P	180	±70	°e
Phase shift	φ	90	±60	°e

Mechanical Notes

| Parameter	Value	Tolerance	Unit
Outer dimensions	Ø 22.0 x 21.9	-	mm
Shaft diameter Øw	1.5 / 2.0 / 2.3 / 2.5 / 3.0 / 3.175 / 3.969 / 4.0 / 4.763 / 5.0 / 6.0 / 6.35 / 8.0 / 9.0 / 9.525	±0.01	mm
Required shaft length L_W	9.5	+2.0	mm
Max. allowable axial shaft play of motor	0.6	-	mm
Max. allowable radial shaft play of motor	0.025	-	mm
Mounting screw size (DIN 84)	M1.6	-	-
Tightening torque of the screws	15	-5	Ncm
Pitch circle diameter Øc	17.0	±1.0	mm
Flange bore diameter diameter $Ø_Z$	7.1 or 10.1	+0.03	mm
Mounting boss diameter Øm	7.1	-0.03	mm
Max. mounting boss height h_Z	1.5	-0.1	mm
Mating connector (Molex)	contact 5x 50079-8000 housing 1x 51021-0500	-	-
Total weight	7	-	g
Moment of inertia of the hub with the code wheel	5.2	±1.0	gmm^2
Protection grade according to DIN 40500	IP50	-	-

Mounting considerations:

The ME22 encoder is designed to self align by using a mounting boss. The drawing shows the configuration of the mounting boss along with the location of the mounting screw holes. Shaft diameter and tolerances are given in the above mentioned chart.

SCHNITT E-E   SCHNITT D-D
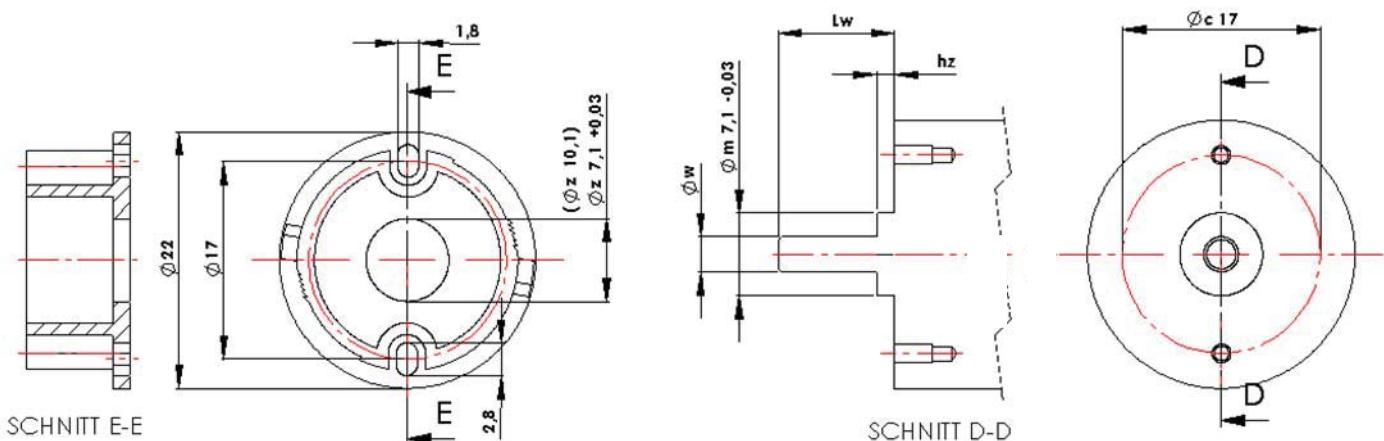
Ordering information

Ordering code:

ME22 - XXX - X.XXX - X - XXX

Encoder Resolution (CPR)*
001 **
002 **
004 **
008 **
050 ***
064 ***
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Motor Shaft Diameter (mm)
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8.000
9.000
9.525 (3/8")

Number of Channels
1 : 1 Channel
2 : 2 Channels
3 : 3 Channels

Output option
LF : connector without cable
LS : connector + standard cable

Note:
* other encoder resolutions on request
** only two channel
*** only one channel

Available accessories see page 9 (no parts of standard delivery):
- cable 300 mm length (UL1061 / AWG28)
- adapter plates for different motors
- centering gauge for different motor shafts
- fastening screws DIN 84 M1.6x3 or M1.6x4